

SUFFICIENCY CLASS FOR GLOBAL (IN TIME) SOLUTIONS TO THE 3D-NAVIER-STOKES EQUATIONS IN \mathbb{V}

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ABSTRACT. Let Ω be an open domain of class \mathbb{C}^3 contained in \mathbb{R}^3 , let $(\mathbb{L}^2[\Omega])^3$ be the real Hilbert space of square integrable functions on Ω with values in \mathbb{R}^3 , and let $\mathbf{D}[\Omega] = \{\mathbf{u} \in (\mathbb{C}_0^\infty[\Omega])^3 \mid \nabla \cdot \mathbf{u} = 0\}$. Let $\mathbb{H}[\Omega]$ be the completion of \mathbf{D} with respect to the inner product of $(\mathbb{L}^2[\Omega])^3$ and let $\mathbb{V}[\Omega]$ be the completion of $\mathbf{D}[\Omega]$ with respect to the inner product of $\mathbb{H}^1[\Omega]$, the functions in $\mathbb{H}[\Omega]$ with weak derivatives in $(\mathbb{L}^2[\Omega])^3$. A well-known unsolved problem is the construction of a sufficient class of functions in $\mathbb{H}[\Omega]$ (respectively $\mathbb{V}[\Omega]$), which will allow global, in time, strong solutions to the three-dimensional Navier-Stokes equations. These equations describe the time evolution of the fluid velocity and pressure of an incompressible viscous homogeneous Newtonian fluid in terms of a given initial velocity and given external body forces. In this paper, we prove that, under appropriate conditions, there exists a number \mathbf{u}_+ , depending only on the domain, the viscosity, the body forces and the eigenvalues of the Stokes operator, such that, for all functions in a dense set \mathbb{D} contained in the closed ball $\mathbb{B}(\Omega)$ of radius \mathbf{u}_+ in $\mathbb{V}[\Omega]$, the Navier-Stokes equations have unique strong solutions in $\mathbb{C}^1((0, \infty), \mathbb{V}[\Omega])$.

INTRODUCTION

Let Ω be an open domain of class \mathbb{C}^3 contained in \mathbb{R}^3 , let $(\mathbb{L}^2[\Omega])^3$ be the real Hilbert space of square integrable functions on Ω with values in \mathbb{R}^3 , let $\mathbf{D}[\Omega]$ be

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$\{\mathbf{u} \in (\mathbb{C}_0^\infty[\Omega])^3 \mid \nabla \cdot \mathbf{u} = 0\}$, let $\mathbb{H}[\Omega]$ be the completion of $\mathbf{D}[\Omega]$ with respect to the inner product of $(\mathbb{L}^2[\Omega])^3$, and let $\mathbb{V}[\Omega]$ be the completion of $\mathbf{D}[\Omega]$ with respect to the inner product of $\mathbb{H}^1[\Omega]$, the functions in $\mathbb{H}[\Omega]$ with weak derivatives in $(\mathbb{L}^2[\Omega])^3$. The global in time classical Navier-Stokes initial-value problem (for $\Omega \subset \mathbb{R}^3$, and all $T > 0$) is to find functions $\mathbf{u} : [0, T] \times \Omega \rightarrow \mathbb{R}^3$, and $p : [0, T] \times \Omega \rightarrow \mathbb{R}$, such that

$$\begin{aligned}
 & \partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} - \nu \Delta \mathbf{u} + \nabla p = \mathbf{f}(t) \text{ in } (0, T) \times \Omega, \\
 & \nabla \cdot \mathbf{u} = 0 \text{ in } (0, T) \times \Omega, \\
 & \mathbf{u}(t, \mathbf{x}) = \mathbf{0} \text{ on } (0, T) \times \partial\Omega \text{ (in the distributional sense),} \\
 & \mathbf{u}(0, \mathbf{x}) = \mathbf{u}_0(\mathbf{x}) \text{ in } \Omega.
 \end{aligned}
 \tag{1}$$

The equations describe the time evolution of the fluid velocity $\mathbf{u}(\mathbf{x}, t)$ and the pressure p of an incompressible viscous homogeneous Newtonian fluid with constant viscosity coefficient ν in terms of a given initial velocity $\mathbf{u}_0(\mathbf{x})$ and given external body forces $\mathbf{f}(\mathbf{x}, t)$.

PURPOSE

Let \mathbb{P} be the (Leray) orthogonal projection of $(\mathbb{L}^2[\Omega])^3$ onto $\mathbb{H}[\Omega]$ and define the Stokes operator by: $\mathbf{A}\mathbf{u} =: -\mathbb{P}\Delta\mathbf{u}$, for $\mathbf{u} \in D(\mathbf{A}) \subset \mathbb{H}^2[\Omega]$, the domain of \mathbf{A} . The purpose of this paper is to prove that there exists a number \mathbf{u}_+ , depending only on \mathbf{A} , f , ν and Ω , such that, for all functions in $\mathbb{D} = D(\mathbf{A}^{3/2}) \cap \mathbb{B}(\Omega)$, where $D(\mathbf{A}^{3/2})$ is the domain of $\mathbf{A}^{3/2}$ and $\mathbb{B}(\Omega)$ is the closed ball of radius \mathbf{u}_+ in $\mathbb{V}(\Omega)$, the Navier-Stokes equations have unique strong solutions in $\mathbf{u} \in L_{\text{loc}}^\infty[[0, \infty); \mathbb{V}(\Omega)] \cap \mathbb{C}^1[[0, \infty); \mathbb{V}(\Omega)]$. We discuss this problem in $\mathbb{H}(\Omega)$, in another paper.

PRELIMINARIES

In terms of notation and conventions, we follow Sell and You [SY]. In order to simplify our proofs, we always assume that all functions \mathbf{u}, \mathbf{v} are in $D(\mathbf{A}^{3/2})$ and we let $c = \max\{c_i\}$, where c_i is one of nine positive constants that appear on pages 363-367 in [SY]. It will also be convenient to use the fact that the norms of $\mathbb{V}[\Omega]$ and $\mathbb{V}[\Omega]^{-1}$ are equivalent to their respective graph norms relative to $\mathbb{H}[\Omega]$. It is known that \mathbf{A} is a positive linear operator with compact resolvent. It follows that the fractional powers $\mathbf{A}^{1/2}$ and $\mathbf{A}^{-1/2}$ are well defined. Moreover, it is also known (cf. [SY], [T1]) that the norms $\|\mathbf{A}^{1/2}\mathbf{u}\|_{\mathbb{H}[\Omega]}$ and $\|\mathbf{A}^{-1/2}\mathbf{u}\|_{\mathbb{H}[\Omega]}$ are equivalent to the corresponding norms induced by the Sobolev space $(H^1[\Omega])^3$, so that:

$$(2) \quad \|\mathbf{u}\|_{\mathbb{V}[\Omega]} \equiv \|\mathbf{A}^{1/2}\mathbf{u}\|_{\mathbb{H}[\Omega]} \quad \text{and} \quad \|\mathbf{u}\|_{\mathbb{V}[\Omega]^{-1}} \equiv \|\mathbf{A}^{-1/2}\mathbf{u}\|_{\mathbb{H}[\Omega]}.$$

In addition, it is known that \mathbf{A} is an isomorphism from $D(\mathbf{A}) \xrightarrow{\text{onto}} \mathbb{H}[\Omega]$, and from $\mathbb{V}[\Omega] \xrightarrow{\text{onto}} \mathbb{V}[\Omega]^{-1}$. Furthermore, the embeddings $\mathbb{V}[\Omega] \rightarrow \mathbb{H}[\Omega] \rightarrow \mathbb{V}[\Omega]^{-1}$ are compact and the operator \mathbf{A}^{-1} is a bounded compact map from $\mathbb{H}[\Omega]$ onto $D(\mathbf{A})$. Applying the Leray projection to equation (1), with $\mathbf{B}(\mathbf{u}, \mathbf{u}) = \mathbb{P}(\mathbf{u} \cdot \nabla)\mathbf{u}$, we can recast equation (1) in the standard form:

$$(3) \quad \begin{aligned} \partial_t \mathbf{u} &= -\nu \mathbf{A}\mathbf{u} - \mathbf{B}(\mathbf{u}, \mathbf{u}) + \mathbb{P}\mathbf{f}(t) \text{ in } (0, T) \times \Omega, \\ \mathbf{u}(t, \mathbf{x}) &= \mathbf{0} \text{ on } (0, T) \times \partial\Omega, \\ \mathbf{u}(0, \mathbf{x}) &= \mathbf{u}_0(\mathbf{x}) \text{ in } \Omega, \end{aligned}$$

where we have used the fact that the orthogonal complement of $\mathbb{H}[\Omega]$ relative to $(\mathbb{L}^2[\Omega])^3$ is $\{\mathbf{v} : \mathbf{v} = \nabla q, q \in (H^1[\Omega])^3\}$ to eliminate the pressure term (see Galdi [GA] or [SY, T1]).

We will use the following inequalities from [SY], pages 363-367. (We use their numbering for easy reference.) Equation (61.8)

$$(4) \quad \|\mathbf{A}^\alpha \mathbf{u}\|_{\mathbb{H}}^2 \geq \lambda_1^{2\alpha} \|\mathbf{u}\|_{\mathbb{H}}^2.$$

Equation (61.26)

$$(5) \quad \begin{aligned} & \left\| \mathbf{A}^{-1/2} \mathbf{B}(\mathbf{u}, \mathbf{v}) \right\|_{\mathbb{H}} \leq c_5 \|\mathbf{u}\|_{\mathbb{H}}^{1/4} \left\| \mathbf{A}^{1/2} \mathbf{u} \right\|_{\mathbb{H}}^{3/4} \|\mathbf{v}\|_{\mathbb{H}}^{1/4} \left\| \mathbf{A}^{1/2} \mathbf{v} \right\|_{\mathbb{H}}^{3/4} \\ & \leq c_5 \lambda_1^{-1/4} \left\| \mathbf{A}^{1/2} \mathbf{u} \right\|_{\mathbb{H}} \left\| \mathbf{A}^{1/2} \mathbf{v} \right\|_{\mathbb{H}} \leq c \lambda_1^{-1/4} \left\| \mathbf{A}^{1/2} \mathbf{u} \right\|_{\mathbb{H}} \left\| \mathbf{A}^{1/2} \mathbf{v} \right\|_{\mathbb{H}}, \\ & \Rightarrow \left\| \mathbf{A}^{-1/2} \mathbf{B}(\mathbf{u}, \mathbf{u}) \right\|_{\mathbb{H}} \leq c \lambda_1^{-1/4} \|\mathbf{u}\|_{\mathbb{V}}^2. \end{aligned}$$

We can use equation (61.21):

$$\|\mathbf{B}(\mathbf{u}, \mathbf{v})\|_{\mathbb{H}} \leq c_1 \|\mathbf{A}\mathbf{u}\|_{\mathbb{H}}^{1/4} \left\| \mathbf{A}^{1/2} \mathbf{u} \right\|_{\mathbb{H}}^{3/4} \|\mathbf{A}\mathbf{v}\|_{\mathbb{H}}^{1/4} \left\| \mathbf{A}^{1/2} \mathbf{v} \right\|_{\mathbb{H}}^{3/4}$$

and the fact that $\lambda_1^{-3/4} \leq \lambda_1^{-1/4}$, along with equation (61.8) to get that:

$$(6) \quad \begin{aligned} & |\langle \mathbf{B}(\mathbf{u}, \mathbf{v}), \mathbf{w} \rangle_{\mathbb{V}}| = |\langle \mathbf{B}(\mathbf{u}, \mathbf{v}), \mathbf{A}\mathbf{w} \rangle_{\mathbb{H}}| \\ & \leq c_1 \left\| \mathbf{A}^{1/2} \mathbf{u} \right\|_{\mathbb{H}}^{3/4} \|\mathbf{A}\mathbf{u}\|_{\mathbb{H}}^{1/4} \left\| \mathbf{A}^{1/2} \mathbf{v} \right\|_{\mathbb{H}}^{3/4} \|\mathbf{A}\mathbf{v}\|_{\mathbb{H}}^{1/4} \|\mathbf{A}\mathbf{w}\|_{\mathbb{H}} \\ & \leq c_1 \lambda_1^{-3/4} \|\mathbf{A}\mathbf{u}\|_{\mathbb{H}} \|\mathbf{A}\mathbf{v}\|_{\mathbb{H}} \|\mathbf{A}\mathbf{w}\|_{\mathbb{H}} \leq c \lambda_1^{-1/4} \|\mathbf{A}\mathbf{u}\|_{\mathbb{H}} \|\mathbf{A}\mathbf{v}\|_{\mathbb{H}} \|\mathbf{A}\mathbf{w}\|_{\mathbb{H}}. \end{aligned}$$

Using the fact that

$$(7) \quad \begin{aligned} & \langle [\mathbf{B}(\mathbf{u}, \mathbf{u}) - \mathbf{B}(\mathbf{v}, \mathbf{v})], \mathbf{u} - \mathbf{v} \rangle_{\mathbb{V}} \\ & = \frac{1}{2} \langle [\mathbf{B}(\mathbf{u} - \mathbf{v}, \mathbf{u}) + \mathbf{B}(\mathbf{u} - \mathbf{v}, \mathbf{v})], \mathbf{A}(\mathbf{u} - \mathbf{v}) \rangle_{\mathbb{H}}, \end{aligned}$$

we have from equation (6) that:

$$(8) \quad \begin{aligned} & \langle [\mathbf{B}(\mathbf{u}, \mathbf{u}) - \mathbf{B}(\mathbf{v}, \mathbf{v})], \mathbf{u} - \mathbf{v} \rangle_{\mathbb{V}} \\ & \leq c \lambda_1^{-1/4} \|\mathbf{A}(\mathbf{u} - \mathbf{v})\|_{\mathbb{H}}^2 \{ \|\mathbf{A}\mathbf{u}\|_{\mathbb{H}} + \|\mathbf{A}\mathbf{v}\|_{\mathbb{H}} \}. \end{aligned}$$

Definition 1. We say that the operator $\mathbf{J}(\cdot, t)$ is (for each t)

- (1) 0-Dissipative if $\langle \mathbf{J}(\mathbf{u}, t), \mathbf{u} \rangle_{\mathbb{V}} \leq 0$.

(2) *Dissipative if $\langle \mathbf{J}(\mathbf{u}, t) - \mathbf{J}(\mathbf{v}, t), \mathbf{u} - \mathbf{v} \rangle_{\mathfrak{V}} \leq 0$.*

(3) *Strongly dissipative if there exists a constant $\alpha > 0$ such that*

$$\langle \mathbf{J}(\mathbf{u}, t) - \mathbf{J}(\mathbf{v}, t), \mathbf{u} - \mathbf{v} \rangle_{\mathfrak{V}} \leq -\alpha \|\mathbf{u} - \mathbf{v}\|_{\mathfrak{V}}^2.$$

Theorem 2 below is essentially due to Browder [B], see Zeidler [Z, Corollary 32.27, page 868 and Corollary 32.35, page 887], while Theorem 3 is from Miyadera [M, p. 185, Theorem 6.20], and is a modification of the Crandall-Liggett Theorem [CL] (see the appendix to the first section of [CL]).

Theorem 2. *Let $\mathbb{B}[\Omega]$ be a closed, bounded, convex subset of $\mathfrak{V}[\Omega]$. If $\mathbf{J}(\cdot, t) : \mathbb{B}[\Omega] \rightarrow \mathfrak{V}[\Omega]$ is closed and strongly dissipative for each fixed $t \geq 0$, then, for each $\mathbf{b} \in \mathbb{B}[\Omega]$, there is a $\mathbf{u} \in \mathbb{B}[\Omega]$ with $\mathbf{J}(\mathbf{u}, t) = \mathbf{b}$ (the range $\text{Ran}[\mathbf{J}(\cdot, t)] \supset \mathbb{B}[\Omega]$).*

Theorem 3. *Let $\{ \mathcal{A}(t), t \in I = [0, \infty) \}$ be a family of operators defined on $\mathfrak{V}[\Omega]$ with domains $D(\mathcal{A}(t)) = D$ independent of t . We assume that $\mathbb{D} = D \cap \mathbb{B}[\Omega]$ is a closed convex set (in an appropriate topology):*

(1) *The operator $\mathcal{A}(t)$ is the generator of a contraction semigroup for each $t \in I$.*

(2) *The function $\mathcal{A}(t)\mathbf{u}$ is continuous in both variables on $I \times \mathbb{D}$.*

Then, for every $\mathbf{u}_0 \in \mathbb{D}$, the problem $\partial_t \mathbf{u}(t, \mathbf{x}) = \mathcal{A}(t)\mathbf{u}(t, \mathbf{x})$, $\mathbf{u}(0, \mathbf{x}) = \mathbf{u}_0(\mathbf{x})$, has a unique solution $\mathbf{u}(t, \mathbf{x}) \in \mathbb{C}^1(I; \mathbb{D})$.

M-DISSIPATIVE CONDITIONS

We assume that $\mathbf{f}(t) \in L^\infty[[0, \infty); \mathfrak{V}(\Omega)]$ and is Lipschitz continuous in t , with $\|\mathbf{f}(t) - \mathbf{f}(\tau)\|_{\mathfrak{V}} \leq d|t - \tau|^\theta$, $d > 0$, $0 < \theta < 1$. We can rewrite equation (3) in the

form:

$$(9) \quad \begin{aligned} \partial_t \mathbf{u} &= \nu \mathbf{A} \mathbf{J}(\mathbf{u}, t) \text{ in } (0, T) \times \Omega, \\ \mathbf{J}(\mathbf{u}, t) &= -\mathbf{u} - \nu^{-1} \mathbf{A}^{-1} \mathbf{B}(\mathbf{u}, \mathbf{u}) + \nu^{-1} \mathbf{A}^{-1} \mathbb{P} \mathbf{f}(t). \end{aligned}$$

APPROACH

We begin with a study of the operator $\mathbf{J}(\cdot, t)$, for fixed t , and seek conditions depending on \mathbf{A} , ν , Ω and $\mathbf{f}(t)$ which guarantee that $\mathbf{J}(\cdot, t)$ is m-dissipative for each t . Clearly $\mathbf{J}(\cdot, t) : D(\mathbf{A}) \xrightarrow{\text{onto}} D(\mathbf{A})$ and, since $\nu \mathbf{A} = \nu \mathbb{P}[-\Delta]$ is a closed positive (m-accretive) operator, so that $-\mathbf{A}$ generates a linear contraction semigroup, we expect that $\nu \mathbf{A} \mathbf{J}(\cdot, t)$ will be m-dissipative for each t .

Theorem 4. *For $t \in I = [0, \infty)$ and, for each fixed \mathbf{u} , $\mathbf{J}(\mathbf{u}, t)$ is Lipschitz continuous, with $\|\mathbf{J}(\mathbf{u}, t) - \mathbf{J}(\mathbf{u}, \tau)\|_{\mathbb{V}} \leq d' |t - \tau|^\theta$, where $d' = d\nu^{-1}(\lambda_1)^{-1}$, d is the Lipschitz constant for the function $\mathbf{f}(t)$ and λ_1 is the first eigenvalue of \mathbf{A} .*

Proof. For fixed \mathbf{u} ,

$$\begin{aligned} \|\mathbf{J}(\mathbf{u}, t) - \mathbf{J}(\mathbf{u}, \tau)\|_{\mathbb{V}} &= \nu^{-1} \|\mathbf{A}^{-1}[\mathbb{P} \mathbf{f}(t) - \mathbb{P} \mathbf{f}(\tau)]\|_{\mathbb{V}} \\ &\leq d\nu^{-1}(\lambda_1)^{-1} |t - \tau|^\theta = d' |t - \tau|^\theta. \end{aligned}$$

We have used the fact that \mathbf{A} is unbounded, and every function $\mathbf{h}(t) \in \mathbb{V}(\Omega)$ has an expansion in terms of the eigenfunctions of \mathbf{A} , so that $\mathbf{A}^{-1} \mathbf{h}(t) = \sum_{k=1}^{\infty} \lambda_k^{-1} h_k(t) \mathbf{e}^k(\mathbf{x})$, and, from here, it is easy to see that $\|\mathbf{A}^{-1} \mathbf{h}(t)\|_{\mathbb{V}} \leq \lambda_1^{-1} \|\mathbf{h}(t)\|_{\mathbb{V}}$. (It is well known that the eigenvalues of \mathbf{A} are positive and increasing (see Temam [T2]).) □

MAIN RESULTS

Theorem 5. *Let $f = \sup_{t \in \mathbb{R}^+} \|\mathbb{P}f(t)\|_{\mathbb{H}} < \infty$, then there exists a positive constant \mathbf{u}_+ , depending only on f , \mathbf{A} , ν and Ω , such that for all \mathbf{u} , with $\|\mathbf{u}\|_{\mathbb{V}} \leq \mathbf{u}_+$, $\mathbf{J}(\cdot, t)$ is strongly dissipative.*

Proof. The proof of our first assertion has two parts. First, we require that the nonlinear operator $\mathbf{J}(\cdot, t)$ be 0-dissipative, which gives us an upper bound \mathbf{u}_+ , in terms of the norm (e.g., $\|\mathbf{u}\|_{\mathbb{V}} \leq \mathbf{u}_+$). We then use this part to show that $\mathbf{J}(\cdot, t)$ is strongly dissipative on the closed ball, $\mathbb{B} = \{\mathbf{u} \in \mathbb{V}(\Omega) : \|\mathbf{u}\|_{\mathbb{V}} \leq \mathbf{u}_+\}$.

Part 1) From equation (7), we have

$$\begin{aligned} \langle \mathbf{J}(\mathbf{u}, t), \mathbf{u} \rangle_{\mathbb{V}} &= - \langle \mathbf{u}, \mathbf{u} \rangle_{\mathbb{V}} - \nu^{-1} \langle \mathbf{A}^{-1} \mathbf{B}(\mathbf{u}, \mathbf{u}) + \mathbf{A}^{-1} \mathbb{P}f(t), \mathbf{u} \rangle_{\mathbb{V}} \\ &\leq - \|\mathbf{u}\|_{\mathbb{V}}^2 + \nu^{-1} \|\mathbf{A}^{-1} \mathbf{B}(\mathbf{u}, \mathbf{u})\|_{\mathbb{V}} \|\mathbf{u}\|_{\mathbb{V}} + \nu^{-1} \|\mathbf{A}^{-1} \mathbb{P}f(t)\|_{\mathbb{V}} \|\mathbf{u}\|_{\mathbb{V}} \\ &= - \|\mathbf{u}\|_{\mathbb{V}}^2 + \nu^{-1} \left\| \mathbf{A}^{-1/2} \mathbf{B}(\mathbf{u}, \mathbf{u}) \right\|_{\mathbb{H}} \|\mathbf{u}\|_{\mathbb{V}} + \nu^{-1} \left\| \mathbf{A}^{-1/2} \mathbb{P}f(t) \right\|_{\mathbb{H}} \|\mathbf{u}\|_{\mathbb{V}} \end{aligned}$$

Using $\|\mathbf{A}^{-1/2} \mathbf{B}(\mathbf{u}, \mathbf{u})\|_{\mathbb{H}} \leq c \lambda_1^{-1/4} \|\mathbf{A}^{1/2} \mathbf{u}\|_{\mathbb{H}}^2$ and $\|\mathbf{A}^{-1/2} \mathbb{P}f(t)\|_{\mathbb{H}} \leq \lambda_1^{-1/2} f$, we have that

$$\begin{aligned} \langle \mathbf{J}(\mathbf{u}, t), \mathbf{u} \rangle_{\mathbb{V}} &\leq - \|\mathbf{u}\|_{\mathbb{V}}^2 + \nu^{-1} c \lambda_1^{-1/4} \|\mathbf{u}\|_{\mathbb{V}}^2 \|\mathbf{u}\|_{\mathbb{V}} + \nu^{-1} \lambda_1^{-1/2} f \|\mathbf{u}\|_{\mathbb{V}} \\ &= - \|\mathbf{u}\|_{\mathbb{V}}^2 + \nu^{-1} c \lambda_1^{-1/4} \|\mathbf{u}\|_{\mathbb{V}}^3 + \nu^{-1} \lambda_1^{-1/2} f \|\mathbf{u}\|_{\mathbb{V}} \leq 0 \\ &\Rightarrow \\ &\|\mathbf{u}\|_{\mathbb{V}} \left\{ \nu^{-1} c \lambda_1^{-1/4} \|\mathbf{u}\|_{\mathbb{V}}^2 - \|\mathbf{u}\|_{\mathbb{V}} + \nu^{-1} \lambda_1^{-1/2} f \right\} \leq 0. \end{aligned}$$

Since $\|\mathbf{u}\|_{\mathbb{V}} > 0$, we can solve to get that:

$$\mathbf{u}_{\pm} = \frac{1}{2} \nu \lambda_1^{1/4} c^{-1} \left\{ 1 \pm \sqrt{1 - [4cf / \lambda_1^{3/4} \nu^2]} \right\} = \frac{1}{2} \nu \lambda_1^{1/4} c^{-1} \left\{ 1 \pm \sqrt{1 - \gamma} \right\}$$

Since we want real distinct solutions, we must require that

$$\gamma = 4cf / \lambda_1^{3/4} \nu^2 < 1 \Rightarrow \lambda_1^{3/4} \nu^2 > 4cf \Rightarrow \nu > 2\lambda_1^{-3/8} (cf)^{1/2}.$$

It follows that if $\mathbb{P}\mathbf{f} \neq \mathbf{0}$, then $\mathbf{u}_- < \mathbf{u}_+$, and our requirement that \mathbf{J} is 0-dissipative implies that

$$\|\mathbf{u}\|_{\mathbb{V}} - \mathbf{u}_+ \leq 0, \quad \|\mathbf{u}\|_{\mathbb{V}} - \mathbf{u}_- \geq 0.$$

This means that, whenever $\mathbf{u}_- \leq \|\mathbf{u}\|_{\mathbb{V}} \leq \mathbf{u}_+$, $\langle \mathbf{J}(\mathbf{u}, t), \mathbf{u} \rangle_{\mathbb{V}} \leq 0$. (It is clear that when $\mathbb{P}\mathbf{f}(t) = \mathbf{0}$, $\mathbf{u}_- = \mathbf{0}$, and $\mathbf{u}_+ = \nu\lambda_1^{1/4}c^{-1}$.)

Part 2): Now, for any $\mathbf{u}, \mathbf{v} \in \mathbb{V}(\Omega)$ with $\max(\|\mathbf{u}\|_{\mathbb{V}}, \|\mathbf{v}\|_{\mathbb{V}}) \leq \mathbf{u}_+$, we have that

$$\begin{aligned} \langle \mathbf{J}(\mathbf{u}, t) - \mathbf{J}(\mathbf{v}, t), \mathbf{u} - \mathbf{v} \rangle_{\mathbb{V}} &= -\|\mathbf{u} - \mathbf{v}\|_{\mathbb{V}}^2 + \frac{1}{2}\nu^{-1} \langle \mathbf{A}^{-1} \{ \mathbf{B}[(\mathbf{u} - \mathbf{v}), \mathbf{u}] + \mathbf{B}[(\mathbf{u} - \mathbf{v}), \mathbf{v}] \}, (\mathbf{u} - \mathbf{v}) \rangle_{\mathbb{V}} \\ &\leq -\|\mathbf{u} - \mathbf{v}\|_{\mathbb{V}}^2 + \frac{1}{2}\nu^{-1} \|\mathbf{u} - \mathbf{v}\|_{\mathbb{V}} (\|\mathbf{A}^{-1}\mathbf{B}[(\mathbf{u} - \mathbf{v}), \mathbf{u}]\|_{\mathbb{V}} + \|\mathbf{A}^{-1}\mathbf{B}[(\mathbf{u} - \mathbf{v}), \mathbf{v}]\|_{\mathbb{V}}) \\ &\leq -\|\mathbf{u} - \mathbf{v}\|_{\mathbb{V}}^2 + \frac{1}{2}c(\nu\lambda_1^{1/4})^{-1} \|\mathbf{u} - \mathbf{v}\|_{\mathbb{V}}^2 (\|\mathbf{u}\|_{\mathbb{V}} + \|\mathbf{v}\|_{\mathbb{V}}) \\ &\leq -\|\mathbf{u} - \mathbf{v}\|_{\mathbb{V}}^2 + c(\nu\lambda_1^{1/4})^{-1} \|\mathbf{u} - \mathbf{v}\|_{\mathbb{V}}^2 (\mathbf{u}_+) \\ &= -\|\mathbf{u} - \mathbf{v}\|_{\mathbb{V}}^2 + c(\nu\lambda_1^{1/4})^{-1} \|\mathbf{u} - \mathbf{v}\|_{\mathbb{V}}^2 \left(\frac{1}{2}\nu\lambda_1^{1/4}c^{-1} \{1 + \sqrt{1 - \gamma}\} \right) \\ &= -\frac{1}{2} \|\mathbf{u} - \mathbf{v}\|_{\mathbb{V}}^2 \{1 - \sqrt{1 - \gamma}\} \\ &= -\alpha \|\mathbf{u} - \mathbf{v}\|_{\mathbb{V}}^2, \quad \alpha = \frac{1}{2} \{1 - \sqrt{1 - \gamma}\}. \end{aligned}$$

It follows that $\mathbf{J}(\mathbf{x}, t)$ is strongly dissipative. \square

Let $\mathbb{B}(\Omega) = \{\mathbf{u} \in \mathbb{V}(\Omega) : \|\mathbf{u}\|_{\mathbb{V}} \leq \mathbf{u}_+\}$, $\mathbb{B}_+(\Omega) = \{\mathbf{u} \in \mathbb{V}(\Omega) : \|\mathbf{A}^{1/2}\mathbf{u}\|_{\mathbb{V}} \leq \mathbf{u}_+\}$ and $\mathbb{B}_{++}(\Omega) = \{\mathbf{u} \in \mathbb{V}(\Omega) : \|\mathbf{A}\mathbf{u}\|_{\mathbb{V}} \leq \mathbf{u}_+\}$. We now show that $\text{Ran}(I - \beta\nu\mathbf{A}\mathbf{J}) \supset \mathbb{B}(\Omega)$, $\beta > 0$.

Theorem 6. *The operator $\mathcal{A}(t) = \nu \mathbf{A}\mathbf{J}(\cdot, t)$ is closed, dissipative and jointly continuous in \mathbf{u} and t . Furthermore, for each $t \in \mathbf{R}^+$ and $\beta > 0$, $\text{Ran}[I - \beta \mathcal{A}(t)] \supset \mathbb{B}[\Omega]$, so that $\mathcal{A}(t)$ is m-dissipative on \mathbb{B}_{++} .*

Proof. Since $\mathbf{J}(\cdot, t)$ is strongly dissipative and closed on $\mathbb{V}[\Omega]$, it follows from Theorem 6 that $\text{Ran}[\mathbf{J}(\cdot, t)] \supset \mathbb{B}[\Omega]$.

To show that $\mathcal{A}(t) = \nu \mathbf{A}\mathbf{J}(\cdot, t)$ is dissipative, first note that for $\mathbf{u}, \mathbf{v} \in \mathbb{B}_+$, and using equation (8), we have

$$\begin{aligned} & \frac{1}{2} \left| \left\langle \mathbf{A}^{1/2} \mathbf{B}(\mathbf{u} - \mathbf{v}, \mathbf{v}), \mathbf{A}^{1/2}(\mathbf{u} - \mathbf{v}) \right\rangle_{\mathbb{H}} + \left\langle \mathbf{A}^{1/2} \mathbf{B}(\mathbf{u} - \mathbf{v}, \mathbf{u}), \mathbf{A}^{1/2}(\mathbf{u} - \mathbf{v}) \right\rangle_{\mathbb{H}} \right| \\ & \leq \frac{1}{2} c \lambda_1^{-1/4} \|\mathbf{A}(\mathbf{u} - \mathbf{v})\|_{\mathbb{H}}^2 (\|\mathbf{A}\mathbf{u}\|_{\mathbb{H}} + \|\mathbf{A}\mathbf{v}\|_{\mathbb{H}}). \end{aligned}$$

Using this result, we have that

$$\begin{aligned} \langle \mathcal{A}(t)\mathbf{u} - \mathcal{A}(t)\mathbf{v}, \mathbf{u} - \mathbf{v} \rangle_{\mathbb{V}} &= -\nu \left\| \mathbf{A}^{1/2}(\mathbf{u} - \mathbf{v}) \right\|_{\mathbb{V}}^2 \\ & - \frac{1}{2} \left\langle \mathbf{A}^{1/2} \mathbf{B}(\mathbf{u} - \mathbf{v}, \mathbf{u}) + \mathbf{A}^{1/2} \mathbf{B}(\mathbf{u} - \mathbf{v}, \mathbf{v}), \mathbf{A}^{1/2}(\mathbf{u} - \mathbf{v}) \right\rangle_{\mathbb{H}} \\ & \leq -\nu \left\| \mathbf{A}^{1/2}(\mathbf{u} - \mathbf{v}) \right\|_{\mathbb{V}}^2 + \frac{1}{2} \lambda_1^{-1/4} c \|\mathbf{A}(\mathbf{u} - \mathbf{v})\|_{\mathbb{H}}^2 (\|\mathbf{A}\mathbf{u}\|_{\mathbb{H}} + \|\mathbf{A}\mathbf{v}\|_{\mathbb{H}}) \\ & = \nu \left\| \mathbf{A}^{1/2}(\mathbf{u} - \mathbf{v}) \right\|_{\mathbb{V}}^2 \left[-1 + \frac{1}{2} c \nu^{-1} \lambda_1^{-1/4} \left(\left\| \mathbf{A}^{1/2} \mathbf{u} \right\|_{\mathbb{V}} + \left\| \mathbf{A}^{1/2} \mathbf{v} \right\|_{\mathbb{V}} \right) \right] \\ & \leq \frac{1}{2} \nu \left\| \mathbf{A}^{1/2}(\mathbf{u} - \mathbf{v}) \right\|_{\mathbb{V}}^2 \left[-1 + c \nu^{-1} \lambda_1^{-1/4} \mathbf{u}_+ \right] \\ & = \frac{1}{2} \nu \left\| \mathbf{A}^{1/2}(\mathbf{u} - \mathbf{v}) \right\|_{\mathbb{V}}^2 \left[-1 + \sqrt{1 - \gamma} \right] < 0. \end{aligned}$$

It follows that $\mathcal{A}(t)$ is dissipative. Since $-\mathbf{A}$ is m-dissipative for $\beta > 0$, $\text{Ran}(I + \beta \mathbf{A}) = \mathbb{V}(\Omega)$. As \mathbf{J} is strongly dissipative, closed, with $\text{Ran}[\mathbf{J}] \supset \mathbb{B}[\Omega]$, and $\mathbf{J}(\cdot, t) : D(\mathbf{A}) \xrightarrow{\text{onto}} D(\mathbf{A})$, $\mathcal{A}(t)$ is maximal dissipative, and also closed, so that $\text{Ran}[I - \beta \mathcal{A}(t)] \supset \mathbb{B}[\Omega]$. It follows that $\mathcal{A}(t)$ is m-dissipative on $\mathbb{B}_+[\Omega]$ for each $t \in \mathbf{R}^+$ (since $\mathbb{V}[\Omega]$ is a Hilbert space). To see that $\mathcal{A}(t)\mathbf{u}$ is continuous in both variables, let $\mathbf{u}_n, \mathbf{u} \in \mathbb{B}_{++}$, $\|\mathbf{A}\mathbf{u}_n - \mathbf{A}\mathbf{u}\|_{\mathbb{V}} \rightarrow 0$, with $t_n, t \in I$ and $t_n \rightarrow t$. Then (see

equation (6))

$$\begin{aligned}
& \|\mathcal{A}(t_n)\mathbf{u}_n - \mathcal{A}(t)\mathbf{u}\|_{\mathbb{V}} \leq \|\mathcal{A}(t_n)\mathbf{u} - \mathcal{A}(t)\mathbf{u}\|_{\mathbb{V}} + \|\mathcal{A}(t_n)\mathbf{u}_n - \mathcal{A}(t_n)\mathbf{u}\|_{\mathbb{V}} \\
& = \|\mathbb{P}\mathbf{f}(t_n) - \mathbb{P}\mathbf{f}(t)\|_{\mathbb{V}} + \left\| \nu \mathbf{A}(\mathbf{u}_n - \mathbf{u}) - \frac{1}{2} [\mathbf{B}(\mathbf{u}_n - \mathbf{u}, \mathbf{u}) + \mathbf{B}(\mathbf{u}_n - \mathbf{u}, \mathbf{u}_n)] \right\|_{\mathbb{V}} \\
& \leq d |t_n - t|^\theta + \nu \|\mathbf{A}(\mathbf{u} - \mathbf{v})\|_{\mathbb{V}} + \frac{1}{2} \left\| \mathbf{A}^{1/2} \mathbf{B}(\mathbf{u}_n - \mathbf{u}, \mathbf{u}) + \mathbf{A}^{1/2} \mathbf{B}(\mathbf{u}_n - \mathbf{u}, \mathbf{u}_n) \right\|_{\mathbb{H}} \\
& \leq d |t_n - t|^\theta + \nu \|\mathbf{A}(\mathbf{u}_n - \mathbf{u})\|_{\mathbb{V}} + \frac{1}{2} \left\| \mathbf{A}^{1/2}(\mathbf{u}_n - \mathbf{u}) \right\|_{\mathbb{H}}^{1/4} \|\mathbf{A}(\mathbf{u}_n - \mathbf{u})\|_{\mathbb{H}}^{3/4} [\|\mathbf{A}\mathbf{u}\|_{\mathbb{H}} + \|\mathbf{A}\mathbf{u}_n\|_{\mathbb{H}}] \\
& \leq d |t_n - t|^\theta + \nu \|\mathbf{A}(\mathbf{u}_n - \mathbf{u})\|_{\mathbb{V}} + \left\| \mathbf{A}^{1/2}(\mathbf{u}_n - \mathbf{u}) \right\|_{\mathbb{H}}^{1/4} \|\mathbf{A}(\mathbf{u}_n - \mathbf{u})\|_{\mathbb{H}}^{3/4} \mathbf{u}_+.
\end{aligned}$$

It follows that $\mathcal{A}(t)\mathbf{u}$ is continuous in both variables. \square

Since $\mathbb{D} = \mathbb{B}_{++}$ is the closure of $D(\mathbf{A}^{3/2}) \cap \mathbb{B}[\Omega]$ equipped with the restriction of the graph norm of $\mathbf{A}^{3/2}$ induced on $D(\mathbf{A}^{3/2})$, it follows that \mathbb{D} is a closed, bounded, convex set. We now have:

Theorem 7. *For each $T \in \mathbf{R}^+$, $t \in (0, T)$ and $\mathbf{u}_0 \in \mathbb{D} \subset \mathbb{B}[\Omega]$, the global in time Navier-Stokes initial-value problem in $\Omega \subset \mathbf{R}^3$:*

$$\begin{aligned}
& \partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} - \nu \Delta \mathbf{u} + \nabla p = \mathbf{f}(t) \text{ in } (0, T) \times \Omega, \\
& \nabla \cdot \mathbf{u} = 0 \text{ in } (0, T) \times \Omega, \\
& \mathbf{u}(t, \mathbf{x}) = \mathbf{0} \text{ on } (0, T) \times \partial\Omega, \\
& \mathbf{u}(0, \mathbf{x}) = \mathbf{u}_0(\mathbf{x}) \text{ in } \Omega.
\end{aligned} \tag{10}$$

has a unique strong solution $\mathbf{u}(t, \mathbf{x})$, which is in $L_{loc}^2[[0, \infty); \mathbb{H}^2(\Omega)]$ and in $L_{loc}^\infty[[0, \infty); \mathbb{V}(\Omega)] \cap \mathcal{C}^1[[0, \infty); \mathbb{V}(\Omega)]$.

Proof. Theorem 6 allows us to conclude that when $\mathbf{u}_0 \in \mathbb{D}$, the initial value problem is solved and the solution $\mathbf{u}(t, \mathbf{x})$ is in $\mathcal{C}^1[[0, \infty); \mathbb{D}(\Omega)]$. Since $\mathbb{D} \subset \mathbb{H}^2[\Omega]$, it follows

that $\mathbf{u}(t, \mathbf{x})$ is also in $\mathbb{V}(\Omega)$, for each $t > 0$. It is now clear that for any $T > 0$,

$$\int_0^T \|\mathbf{u}(t, \mathbf{x})\|_{\mathbb{H}[\Omega]}^2 dt < \infty, \text{ and } \sup_{0 < t < T} \|\mathbf{u}(t, \mathbf{x})\|_{\mathbb{V}[\Omega]}^2 < \infty.$$

This gives our conclusion. \square

DISCUSSION

It is clear from our results that the stationary problem also has a unique solution in $\mathbb{B}_+[\Omega]$. It is also known that, if $\mathbf{u}_0 \in \mathbb{V}$ and $\mathbf{f}(t)$ is $L^\infty[(0, \infty), \mathbb{H}]$, then there is a time $T > 0$ such that a weak solution with this data is uniquely determined on any subinterval of $[0, T)$ (see Sell and You, page 396, [SY]). Thus, we also have that:

Corollary 8. *For each $t \in \mathbf{R}^+$ and $\mathbf{u}_0 \in \mathbb{D}$ the Navier-Stokes initial-value problem in $\Omega \subset \mathbb{R}^3$:*

$$\begin{aligned} \partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} - \nu \Delta \mathbf{u} + \nabla p &= \mathbf{f}(t) \text{ in } (0, T) \times \Omega, \\ \nabla \cdot \mathbf{u} &= 0 \text{ in } (0, T) \times \Omega, \\ \mathbf{u}(t, \mathbf{x}) &= \mathbf{0} \text{ on } (0, T) \times \partial\Omega, \\ \mathbf{u}(0, \mathbf{x}) &= \mathbf{u}_0(\mathbf{x}) \text{ in } \Omega. \end{aligned} \tag{11}$$

has a unique weak solution $\mathbf{u}(t, \mathbf{x})$ which is in $L_{loc}^2[[0, \infty); \mathbb{H}^2(\Omega)]$ and in $L_{loc}^\infty[[0, \infty); \mathbb{V}(\Omega)] \cap \mathbb{C}^1[[0, \infty); \mathbb{H}(\Omega)]$.

Since we require that our initial data be in $\mathbb{H}^{3/2}[\Omega]$, the conditions for the Leray-Hopf weak solutions are not satisfied. However, it was an open question as to whether these solutions developed singularities, even if $\mathbf{u}_0 \in \mathbb{C}_0^\infty[\Omega]$ (see Giga [G], and references therein). The above Corollary shows that it suffices that $\mathbf{u}_0(\mathbf{x}) \in \mathbb{H}^2(\Omega)$ to insure that the solutions develop no singularities.

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