

- Reminder:
- 1st HW due Thursday in class
 - Class mds at <http://www.ma.utexas.edu/users/neitzke>
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- Last time:
- Systems of linear equations, their augmented matrices
 - Row equivalence
 - Row echelon form (REF), reduced row echelon form (RREF)
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Recall Fact: Every matrix is row equivalent to one in RREF.
(The RREF is unique.)

Algorithm for putting a matrix in REF by row operations:

eg.
$$\begin{bmatrix} 0 & * & * & * \\ \blacksquare & * & * & * \\ * & * & * & * \end{bmatrix}$$

* = anything

\blacksquare = anything not zero

- 1) By swapping rows, make the leftmost nonzero entry be in the top row.

$$\rightarrow \begin{bmatrix} \blacksquare & * & * & * \\ 0 & * & * & * \\ * & * & * & * \end{bmatrix}$$

- 2) "Clean out" the first column containing nonzero entries, by adding multiples of the top row to the other rows

$$\rightarrow \begin{bmatrix} \blacksquare & * & * & * \\ 0 & * & * & * \\ 0 & * & * & * \end{bmatrix}$$

3) Set aside the top row, work on the rest of the matrix.

$$\begin{bmatrix} \blacksquare & * & * & * \\ \hline 0 & * & * & * \\ 0 & * & * & * \end{bmatrix}$$

Repeat steps 1-3 until matrix is in REF.

Algorithm for putting matrix in RREF by row ops:

Do 1-3 repeatedly as above. Get a matrix in REF

$$\begin{bmatrix} 0 & \blacksquare & * & * & * & * \\ 0 & 0 & 0 & \blacksquare & * & * \\ 0 & 0 & 0 & 0 & \blacksquare & * \end{bmatrix}$$

4) Rescale each row to make the pivots 1

$$\rightarrow \begin{bmatrix} 0 & \textcircled{1} & * & * & * & * \\ 0 & 0 & 0 & \textcircled{1} & * & * \\ 0 & 0 & 0 & 0 & \textcircled{1} & * \end{bmatrix}$$

5) Working from R to L, use each pivot to "clear out" the entries above it, by adding multiples of the row containing pivot to other rows

$$\rightarrow \begin{bmatrix} 0 & \textcircled{1} & * & 0 & 0 & * \\ 0 & 0 & 0 & \textcircled{1} & 0 & * \\ 0 & 0 & 0 & 0 & \textcircled{1} & * \end{bmatrix}$$

Once we have put the augmented matrix of some linear system in RREF we can easily read off the solutions.

Ex If RREF of aug. matrix is

$$\left[\begin{array}{ccccccc|c} \textcircled{1} & 0 & 0 & 2 & 0 & 7 & 0 & -4 \\ 0 & \textcircled{1} & 0 & 3 & 0 & 4 & 0 & 8 \\ 0 & 0 & \textcircled{1} & -1 & 0 & 5 & 0 & 3 \\ 0 & 0 & 0 & 0 & \textcircled{1} & 2 & 0 & 7 \\ 0 & 0 & 0 & 0 & 0 & 0 & \textcircled{1} & 3 \end{array} \right] \rightsquigarrow \begin{array}{l} x_1 + 2x_4 + 7x_6 = -4 \\ x_2 + 3x_4 + 4x_6 = 8 \\ x_3 - x_4 + 5x_6 = 3 \\ x_5 + 2x_6 = 7 \\ x_7 = 3 \end{array}$$

Call the variables corresponding to pivot columns "basic variables"
[Here x_1, x_2, x_3, x_5, x_7 are basic]

Write sol's as eq for basic vars:

$$\left[\begin{array}{l} x_1 = -4 - 2x_4 - 7x_6 \\ x_2 = 8 - 3x_4 - 4x_6 \\ x_3 = 3 + x_4 - 5x_6 \\ x_5 = 7 - 2x_6 \\ x_7 = 3 \\ x_4 = \text{anything} \\ x_6 = \text{anything} \end{array} \right] \leftarrow \text{[Solution set]}$$

Call the non-basic variables "free variables."

[Here x_4, x_6 are free]

This system is consistent, has infinitely many solutions

(Any consistent sys. w/ free variables has infinitely many sol's)

$$\underline{\text{Ex}} \quad \left[\begin{array}{ccc|c} \textcircled{1} & 0 & 0 & -2 \\ 0 & \textcircled{1} & 0 & 3 \\ 0 & 0 & \textcircled{1} & 4 \end{array} \right] \rightsquigarrow \begin{array}{l} x_1 = -2 \\ x_2 = 3 \\ x_3 = 4 \end{array}$$

all vars basic — no free vars

Consistent, has unique solution

$$\underline{\text{Ex}} \quad \left[\begin{array}{cccc|c} \textcircled{1} & 0 & 5 & 2 & 0 \\ 0 & \textcircled{1} & 3 & -1 & 0 \\ 0 & 0 & 0 & 0 & \textcircled{1} \end{array} \right] \rightsquigarrow \begin{array}{l} x_1 + 5x_3 + 2x_4 = 0 \\ x_2 + 3x_3 - x_4 = 0 \\ 0 = 1 \leftarrow ! \end{array}$$

x_1, x_2 basic
 x_3, x_4 free

Inconsistent — no solⁿ (even tho there are free vars)

Whenever the RREF of aug. mat. has pivot in last column the system is inconsistent.

Last note: to see free/basic vars
and consistent/inconsistent

REF is enough — don't need RREF.

Vectors and Vector Equations (Sec 1.3)

(For now): A (column) vector is a set of real numbers arranged in a column:

$$\text{Ex } \begin{bmatrix} 4 \\ -2 \\ 3 \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ 8 \end{bmatrix}, \begin{bmatrix} 0 \\ 6 \\ -2 \\ 0 \end{bmatrix} \in \mathbb{R}^4$$

\uparrow \mathbb{R}^3 \uparrow \mathbb{R}^2

The set of all vectors with n entries is called \mathbb{R}^n .

Denote vectors by e.g. $\vec{x}, \vec{y}, \vec{u}, \dots$ (or bold letters)

Use $\vec{0}$ for zero vector e.g. $\vec{0} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \in \mathbb{R}^3$

We can add vectors: by adding their entries

so e.g. if $\vec{x} = \begin{bmatrix} -1 \\ 7 \end{bmatrix}$ $\vec{y} = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$

then $\vec{x} + \vec{y} = \begin{bmatrix} -1 + 4 \\ 7 + 2 \end{bmatrix} = \begin{bmatrix} 3 \\ 9 \end{bmatrix}$

But, we can only add vectors of the same length

e.g. $\begin{bmatrix} 2 \\ -2 \\ 3 \end{bmatrix} + \begin{bmatrix} 4 \\ 1 \end{bmatrix}$ doesn't make sense (is undefined)

Scalar multiplication: if c is a constant ("scalar")

and \vec{x} is a vector

then $c\vec{x}$ is the vector obtained by multiplying each entry of \vec{x} by c .

Ex $4 \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 4 \\ 12 \end{bmatrix}$

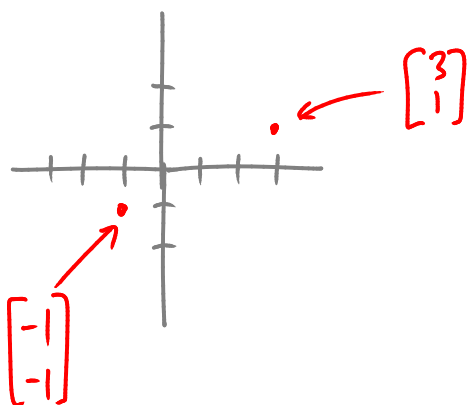
$$-3 \begin{bmatrix} 5 \\ 0 \\ -2 \end{bmatrix} = \begin{bmatrix} -15 \\ 0 \\ 6 \end{bmatrix}$$

$$0 \begin{bmatrix} -4 \\ 7 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \vec{0}$$

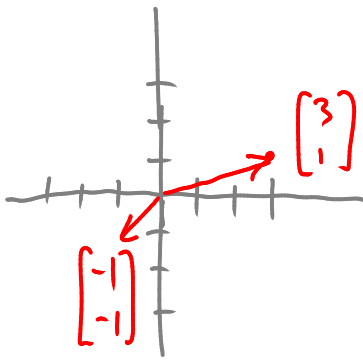
Notation: also write $-\vec{x}$ for the vector $(-1)\vec{x}$.

Picturing \mathbb{R}^2

We identify a vector $\begin{bmatrix} x \\ y \end{bmatrix}$ with a point (x, y) of the plane.

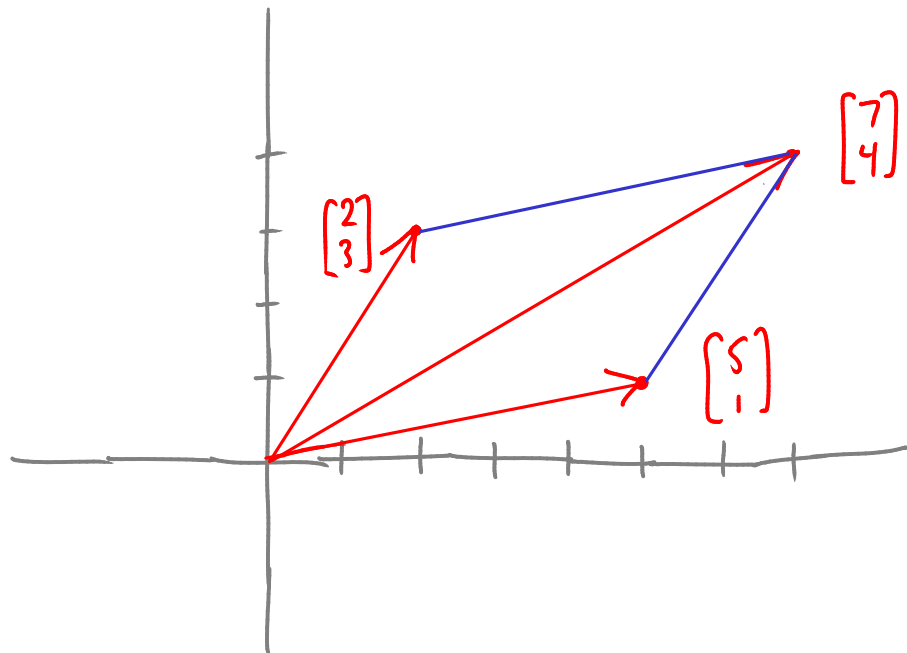


Sometimes also represent them as arrows from the origin:

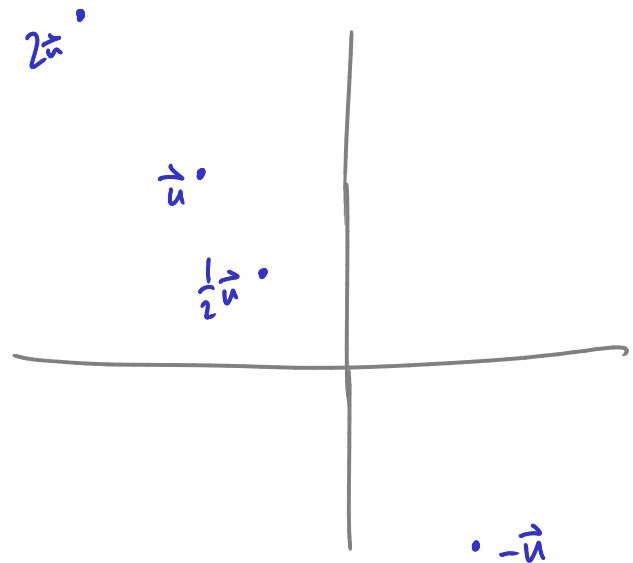
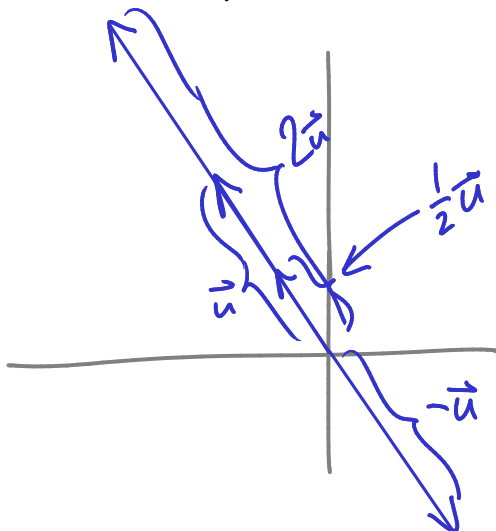


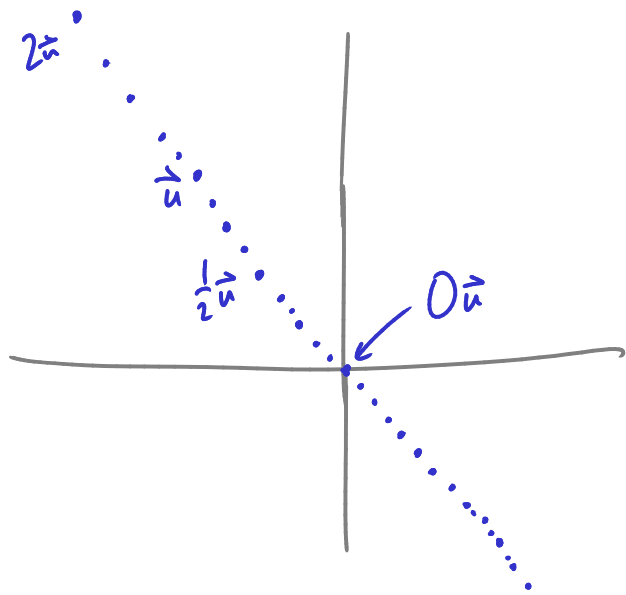
Addition of vectors in \mathbb{R}^2 can be pictured via the "parallelogram law":

Ex $\begin{bmatrix} 5 \\ 1 \end{bmatrix} + \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \end{bmatrix}$



Scalar multiplication rescales the length of a vector





The set of all scalar multiples $c\vec{u}$ makes up a line.
(through the origin)

Can also picture vectors in \mathbb{R}^3 similarly: $\begin{bmatrix} x \\ y \\ z \end{bmatrix} \leftrightarrow \text{point } (x, y, z)$

Linear combinations

A vector of the form

$$\vec{y} = c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_p\vec{v}_p$$

is called a linear combination of the vectors $\vec{v}_1, \dots, \vec{v}_p$.

Ex
$$\begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix} = 2 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + (-1) \begin{bmatrix} -1 \\ -1 \\ 2 \end{bmatrix}$$

so $\begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}$ is a lin. comb. of $\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} -1 \\ -1 \\ 2 \end{bmatrix}$.

$$\underline{\text{Ex}} \quad \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

So $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ is a lin. comb. of $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$
(for any $x_1, x_2!$)

$$\underline{\text{Ex}} \quad \vec{a}_1 = \begin{bmatrix} 2 \\ 1 \\ 4 \end{bmatrix} \quad \vec{a}_2 = \begin{bmatrix} -5 \\ 7 \\ 5 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 1 \\ 10 \\ 17 \end{bmatrix}$$

Is \vec{b} a lin comb of \vec{a}_1, \vec{a}_2 ? (If so, with what weights?)

i.e: Do there exist x_1, x_2 such that $x_1 \vec{a}_1 + x_2 \vec{a}_2 = \vec{b}$?
If so, what are they?

$$\text{i.e.} \quad \begin{bmatrix} 2x_1 \\ x_1 \\ 4x_1 \end{bmatrix} + \begin{bmatrix} -5x_2 \\ 7x_2 \\ 5x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 10 \\ 17 \end{bmatrix}$$

$$\text{i.e.} \quad \begin{bmatrix} 2x_1 - 5x_2 \\ x_1 + 7x_2 \\ 4x_1 + 5x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 10 \\ 17 \end{bmatrix}$$

Linear system for the variables x_1, x_2 .

$$\text{Aug. matrix:} \quad \left[\begin{array}{cc|c} 2 & -5 & 1 \\ 1 & 7 & 10 \\ 4 & 5 & 17 \end{array} \right] = \left[\vec{a}_1 \quad \vec{a}_2 \mid \vec{b} \right]$$

REF: $\sim \left[\begin{array}{cc|c} 1 & 0 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{array} \right] \quad \begin{array}{l} x_1 = 3 \\ x_2 = 1 \end{array}$

So $3\vec{a}_1 + \vec{a}_2 = \vec{b}$

i.e. \vec{b} is a lin. comb. of \vec{a}_1 and \vec{a}_2 , with weights $c_1 = 3$ and $c_2 = 1$.

Fact: \vec{b} is a lin. comb. of $\vec{a}_1, \dots, \vec{a}_p$

\Updownarrow (if and only if)

The lin. sys. represented by aug. matrix

$$\left[\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_p \mid \vec{b} \right]$$

is consistent