

$$P_{\vec{a}} \vec{b} = \left( \frac{\vec{a} \cdot \vec{b}}{\vec{a} \cdot \vec{a}} \right) \vec{a} = \hat{x} \vec{a}$$

If  $\vec{a}$  is a unit vector,  $\vec{a} \cdot \vec{a} = 1$ ,

$$P_{\vec{a}} \vec{b} = (\vec{a} \cdot \vec{b}) \vec{a} = \hat{x} \vec{a} \quad \hat{x} = \vec{a} \cdot \vec{b}$$

$$P_{\vec{a}} = \vec{a} \vec{a}^T$$

If  $A = (\vec{a}_1 \dots \vec{a}_n)$   $V = \text{col}(A) = \text{Span} \{ \vec{a}_1, \dots, \vec{a}_n \}$

To get  $P_V \vec{b}$ , solve  $A^T A \vec{x} = A^T \vec{b}$ , then

$$P_V \vec{b} = A \vec{x}$$

If columns of  $A$  are lin ind,  $A^T A$  is invertible,

$$\vec{x} = (A^T A)^{-1} A^T \vec{b}, \quad P_V \vec{b} = A (A^T A)^{-1} A^T \vec{b}$$

$$P_V = A (A^T A)^{-1} A^T$$

Thm If columns of  $A$  are  $\perp$ ,

$$\text{then } P_V = P_{\vec{a}_1} + P_{\vec{a}_2} + \dots + P_{\vec{a}_n}.$$

Restatement: If  $\vec{a}_1, \dots, \vec{a}_n$  are orthogonal and  $b$  is any vector, then

$$\vec{b} = \left( \frac{(\vec{a}_1 \cdot \vec{b})}{\vec{a}_1 \cdot \vec{a}_1} \right) \vec{a}_1 + \dots + \frac{(\vec{a}_n \cdot \vec{b})}{(\vec{a}_n \cdot \vec{a}_n)} \vec{a}_n + \vec{b}_\perp,$$

where  $b_\perp \in V^\perp$ .

Special case: If  $\vec{a}_1, \dots, \vec{a}_n$  are orthonormal,

then

$$\vec{b} = (\vec{a}_1 \cdot \vec{b}) \vec{a}_1 + \dots + (\vec{a}_n \cdot \vec{b}) \vec{a}_n + \vec{b}_\perp.$$

$$P_V = \vec{a}_1 \vec{a}_1^T + \vec{a}_2 \vec{a}_2^T + \dots + \vec{a}_n \vec{a}_n^T$$

Counter examples.

$$\text{In } \mathbb{R}^2, \quad \vec{a}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \quad \vec{a}_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

$$\vec{b} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}.$$

$$\frac{\vec{a}_1 \cdot \vec{b}}{\vec{a}_1 \cdot \vec{a}_1} \vec{a}_1 = \frac{5}{5} \vec{a}_1 = \vec{a}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$\frac{\vec{a}_2 \cdot \vec{b}}{\vec{a}_2 \cdot \vec{a}_2} = \frac{4}{5} \vec{a}_2 = \begin{pmatrix} 4/5 \\ 8/5 \end{pmatrix}$$

$$P_V \neq P_{\vec{a}_1} + P_{\vec{a}_2} \quad \text{Since } \vec{a}_1 \text{ and } \vec{a}_2 \text{ are not } \perp$$

$$\text{In } \mathbb{R}^2, \quad \vec{a}_1 = \begin{pmatrix} 2 \\ 0 \end{pmatrix}, \quad \vec{a}_2 = \begin{pmatrix} 0 \\ -2 \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} 3 \\ 5 \end{pmatrix}$$

$$\vec{b} = \frac{6}{4} \vec{a}_1 + \frac{10}{4} \vec{a}_2 \neq 6\vec{a}_1 + 10\vec{a}_2$$

$$\vec{a}_1 \cdot \vec{a}_1$$

$$\vec{a}_2 \cdot \vec{a}_2$$

Proof of thm

$$\vec{b} = \vec{b}_{||} + \vec{b}_{\perp}$$

$$= c_1 \vec{a}_1 + \dots + c_n \vec{a}_n + \vec{b}_{\perp}$$

$$\begin{aligned} \vec{a}_1 \cdot \vec{b} &= c_1 \vec{a}_1 \cdot \vec{a}_1 + c_2 \vec{a}_1 \cdot \vec{a}_2 + \dots + c_n \vec{a}_1 \cdot \vec{a}_n + \vec{a}_1 \cdot \vec{b}_{\perp} \\ &= c_1 \vec{a}_1 \cdot \vec{a}_1 \end{aligned}$$

$$\Rightarrow c_1 = \frac{\vec{a}_1 \cdot \vec{b}}{\vec{a}_1 \cdot \vec{a}_1}, \quad c_k = \frac{\vec{a}_k \cdot \vec{b}}{\vec{a}_k \cdot \vec{a}_k}$$

$$\vec{b} = \left( \frac{\vec{a}_1 \cdot \vec{b}}{\vec{a}_1 \cdot \vec{a}_1} \right) \vec{a}_1 + \dots + \left( \frac{\vec{a}_n \cdot \vec{b}}{\vec{a}_n \cdot \vec{a}_n} \right) \vec{a}_n + \vec{b}_{\perp}$$

$$A = \begin{pmatrix} 1 & 2 & 6 \\ 1 & 4 & 0 \\ 1 & 6 & -2 \\ 1 & 8 & 0 \end{pmatrix} = \begin{pmatrix} \vec{a}_1 & \vec{a}_2 & \vec{a}_3 \end{pmatrix}$$

Find an orthogonal basis for  $\text{Col}(A)$ .

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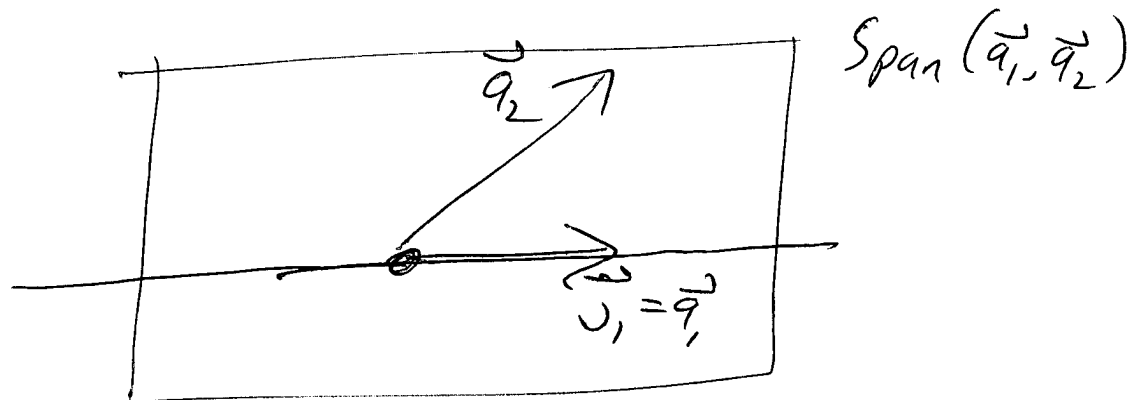
Gram-Schmidt (sp?) process

Idea: For each  $k=1, \dots, n$ , we want

$(\vec{v}_1, \dots, \vec{v}_k)$  to be an orthogonal basis for  $\text{Span}(\vec{a}_1, \dots, \vec{a}_k)$

Step 1:  $\vec{v}_1 = \vec{a}_1$ .

Step 2:

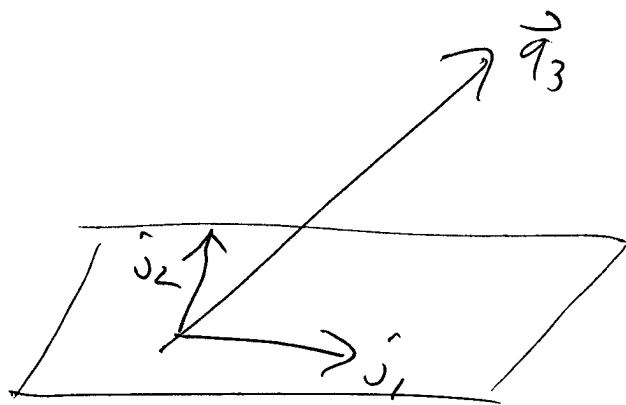


$\vec{v}_2 = (\vec{a}_2)_\perp = \text{part of } \vec{a}_2 \perp \text{ to } \vec{v}_1$ .

$$= \vec{a}_2 - P_{\vec{v}_1} \vec{a}_2$$

$$= \vec{a}_2 - \left( \frac{\vec{a}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \right) \vec{v}_1$$

Step 3



$\vec{v}_3 = (\vec{a}_3)_\perp = \text{part of } \vec{a}_3 \perp \text{ to } \text{Span}\{\vec{v}_1, \vec{v}_2\}$

$$= \vec{a}_3 - P_{\vec{v}_1} \vec{a}_3 - P_{\vec{v}_2} \vec{a}_3$$

Step 4

$$\vec{J}_4 = \vec{a}_4 - P_{j_1} \vec{a}_4 - P_{j_2} \vec{a}_4 - P_{j_3} \vec{a}_4$$

Step k

$$\vec{J}_k = \vec{a}_k - P_{j_1} \vec{a}_k - \dots - P_{j_{k-1}} \vec{a}_k$$

$(\vec{a}_k) \perp$

NOT  $\vec{a}_k = \sum_{i=1}^{k-1} P_{\vec{a}_i} \vec{a}_k$

Example

$$A = \begin{pmatrix} 1 & 2 & 6 \\ 1 & 4 & 0 \\ 1 & 6 & -2 \\ 1 & 8 & 0 \end{pmatrix}$$

$$\vec{v}_1 = \vec{q}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\vec{v}_2 = \vec{q}_2 - P_{j_1} \vec{q}_2 = \vec{q}_2 - \frac{20}{4} \vec{v}_1 = \begin{pmatrix} -3 \\ -1 \\ 1 \\ 3 \end{pmatrix}$$

$$\begin{aligned} \vec{v}_3 &= \vec{q}_3 - P_{j_1} \vec{q}_3 - P_{j_2} \vec{q}_3 = \vec{q}_3 - \left( \frac{\vec{v}_1 \cdot \vec{q}_3}{\vec{v}_1 \cdot \vec{v}_1} \right) \vec{v}_1 - \left( \frac{\vec{v}_2 \cdot \vec{q}_3}{\vec{v}_2 \cdot \vec{v}_2} \right) \vec{v}_2 \\ &= \vec{q}_3 - \frac{4}{4} \vec{v}_1 - \frac{(-20)}{20} \vec{v}_2 = \begin{pmatrix} 6 \\ 0 \\ -2 \\ 0 \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} + \begin{pmatrix} -3 \\ -1 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 2 \\ -2 \\ -2 \\ 2 \end{pmatrix} \end{aligned}$$

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$$\vec{v}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|} = \frac{\vec{v}_1}{\sqrt{\vec{v}_1 \cdot \vec{v}_1}} = \frac{1}{\sqrt{4}} \vec{v}_1 = \begin{pmatrix} 1/2 \\ 1/2 \\ 1/2 \\ 1/2 \end{pmatrix}$$



$$\vec{q}_2 = \frac{\vec{j}_2}{|\vec{j}_2|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} -3 \\ -1 \\ 1 \\ 3 \end{pmatrix}$$

$$\vec{q}_3 = \frac{\vec{j}_3}{|\vec{j}_3|} = \frac{1}{4} \vec{j}_3 = \begin{pmatrix} 1/2 \\ -1/2 \\ -1/2 \\ 1/2 \end{pmatrix}$$

$$\text{Span} \{ \vec{q}_1, \vec{q}_2, \vec{q}_3 \} = \text{Span} \{ \vec{a}_1, \vec{a}_2, \vec{a}_3 \}.$$

$$\text{For any } \vec{b} \in \text{Span}(\vec{a}_1, \vec{a}_2, \vec{a}_3)$$

$$\vec{b} = (\vec{b} \cdot \vec{q}_1) \vec{q}_1 + (\vec{b} \cdot \vec{q}_2) \vec{q}_2 + (\vec{b} \cdot \vec{q}_3) \vec{q}_3.$$

$$\vec{a}_1 = (\vec{a}_1 \cdot \vec{q}_1) \vec{q}_1$$

$$\vec{a}_2 = (\vec{a}_2 \cdot \vec{q}_1) \vec{q}_1 + (\vec{a}_2 \cdot \vec{q}_2) \vec{q}_2$$

$$\vec{a}_3 = (\vec{a}_3 \cdot \vec{q}_1) \vec{q}_1 + (\vec{a}_3 \cdot \vec{q}_2) \vec{q}_2 + (\vec{a}_3 \cdot \vec{q}_3) \vec{q}_3$$

$$A = \begin{pmatrix} \vec{a}_1 & \vec{a}_2 & \vec{a}_3 \end{pmatrix} \quad Q = \begin{pmatrix} \vec{q}_1 & \vec{q}_2 & \vec{q}_3 \end{pmatrix}$$

$$A = QR$$

$$R = \begin{pmatrix} (\vec{a}_1 \cdot \vec{q}_1) & \vec{a}_2 \cdot \vec{q}_1 & \vec{a}_3 \cdot \vec{q}_1 \\ 0 & (\vec{a}_2 \cdot \vec{q}_2) & \vec{a}_3 \cdot \vec{q}_2 \\ 0 & 0 & \vec{a}_3 \cdot \vec{q}_3 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 2 & 6 \\ 1 & 4 & 0 \\ 1 & 6 & -2 \\ 1 & 8 & 0 \end{pmatrix}$$

$$Q = \begin{pmatrix} 1/2 & \frac{-3}{2\sqrt{5}} & 1/2 \\ 1/2 & \frac{-1}{2\sqrt{5}} & -1/2 \\ 1/2 & 1/2\sqrt{5} & -1/2 \\ 1/2 & 3/2\sqrt{5} & 1/2 \end{pmatrix}$$

$$\vec{a}_1 \cdot \vec{q}_1 = 2$$

$$\vec{a}_2 \cdot \vec{q}_1 = 10$$

$$\vec{a}_2 \cdot \vec{q}_2 = \frac{20}{2\sqrt{5}} = 2\sqrt{5}$$

$$\vec{a}_3 \cdot \vec{q}_1 = 2$$

$$\vec{a}_3 \cdot \vec{q}_2 = -2\sqrt{5}$$

$$\vec{a}_3 \cdot \vec{q}_3 = 4$$

$${}^m \begin{pmatrix} 1 & 2 & 6 \\ 1 & 4 & 0 \\ 1 & 6 & -2 \\ 1 & 8 & 0 \end{pmatrix} \stackrel{n}{=} {}^m \begin{pmatrix} 1/2 & \frac{-3}{2\sqrt{5}} & 1/2 \\ 1/2 & \frac{-1}{2\sqrt{5}} & -1/2 \\ 1/2 & 1/2\sqrt{5} & -1/2 \\ 1/2 & 3/2\sqrt{5} & 1/2 \end{pmatrix} \stackrel{n}{=} \begin{pmatrix} 2 & 10 & 2 \\ 0 & 2\sqrt{5} & -2\sqrt{5} \\ 0 & 0 & 4 \end{pmatrix}$$

$$Q^T Q = \begin{pmatrix} q_1^T \\ q_2^T \\ q_3^T \end{pmatrix} (q_1 \ q_2 \ q_3)$$

$$= \begin{pmatrix} q_1 \cdot q_1 & q_1 \cdot q_2 & q_1 \cdot q_3 \\ q_2 \cdot q_1 & - & - \\ - & - & - \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

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$$A^T A \hat{x} = A^T b$$

$$R^T Q^T Q R \hat{x} = R^T Q^T b$$

$$R^T R \hat{x} = R^T Q^T b$$

$$\boxed{R \hat{x} = Q^T b}$$